# 问题与讨论

2014-11-12

- 25.1-4/5/10
- 25.2-4
- 25.3-2/3
- 25-2

#### 25.1-4

Show that matrix multiplication defined by EXTEND-SHORTEST-PATHS is associative.

#### 25.1-5

Show how to express the single-source shortest-paths problem as a product of matrices and a vector. Describe how evaluating this product corresponds to a Bellman-Ford-like algorithm (see Section 24.1).

```
EXTEND-SHORTEST-PATHS (L, W)

1 n = L.rows

2 let L' = (l'_{ij}) be a new n \times n matrix

3 for i = 1 to n

4 for j = 1 to n

5 l'_{ij} = \infty

6 for k = 1 to n

7 l'_{ij} = \min(l'_{ij}, l_{ik} + w_{kj})

8 return L'
```

```
SLOW-ALL-PAIRS-SHORTEST-PATHS (W)

1 n = W.rows

2 L^{(1)} = W

3 for m = 2 to n - 1

4 let L^{(m)} be a new n \times n matrix

5 L^{(m)} = \text{EXTEND-SHORTEST-PATHS}(L^{(m-1)}, W)

6 return L^{(n-1)}
```

# 25.1-10

Give an efficient algorithm to find the length (number of edges) of a minimumlength negative-weight cycle in a graph.

#### 25.2-4

As it appears above, the Floyd-Warshall algorithm requires  $\Theta(n^3)$  space, since we compute  $d_{ij}^{(k)}$  for i, j, k = 1, 2, ..., n. Show that the following procedure, which simply drops all the superscripts, is correct, and thus only  $\Theta(n^2)$  space is required.

# FLOYD-WARSHALL'(W)

```
1 n = W.rows

2 D = W

3 \mathbf{for} \ k = 1 \mathbf{to} \ n

4 \mathbf{for} \ i = 1 \mathbf{to} \ n

5 \mathbf{for} \ j = 1 \mathbf{to} \ n

6 d_{ij} = \min(d_{ij}, d_{ik} + d_{kj})

7 \mathbf{return} \ D
```

$$d_{ij}^{(k)} \leftarrow \min \left( d_{ij}^{(k-1)}, d_{ik}^{(k)} + d_{kj}^{(k-1)} \right)$$

$$d_{ij}^{(k)} \leftarrow \min \left( d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k)} \right)$$

$$d_{ij}^{(k)} \leftarrow \min \left( d_{ij}^{(k-1)}, d_{ik}^{(k)} + d_{kj}^{(k)} \right)$$

## 25.3-2

What is the purpose of adding the new vertex s to V, yielding V'?

## *25.3-3*

Suppose that  $w(u, v) \ge 0$  for all edges  $(u, v) \in E$ . What is the relationship between the weight functions w and  $\hat{w}$ ?

# 25-2 Shortest paths in $\epsilon$ -dense graphs

A graph G = (V, E) is  $\epsilon$ -dense if  $|E| = \Theta(V^{1+\epsilon})$  for some constant  $\epsilon$  in the range  $0 < \epsilon \le 1$ . By using d-ary min-heaps (see Problem 6-2) in shortest-paths algorithms on  $\epsilon$ -dense graphs, we can match the running times of Fibonacci-heap-based algorithms without using as complicated a data structure.

a. What are the asymptotic running times for INSERT, EXTRACT-MIN, and DECREASE-KEY, as a function of d and the number n of elements in a d-ary min-heap? What are these running times if we choose  $d = \Theta(n^{\alpha})$  for some constant  $0 < \alpha \le 1$ ? Compare these running times to the amortized costs of these operations for a Fibonacci heap.

## 6-2 Analysis of d-ary heaps

A *d-ary heap* is like a binary heap, but (with one possible exception) non-leaf nodes have *d* children instead of 2 children.

- a. How would you represent a d-ary heap in an array?
- b. What is the height of a d-ary heap of n elements in terms of n and d?
- c. Give an efficient implementation of EXTRACT-MAX in a d-ary max-heap. Analyze its running time in terms of d and n.
- d. Give an efficient implementation of INSERT in a d-ary max-heap. Analyze its running time in terms of d and n.
- e. Give an efficient implementation of INCREASE-KEY (A, i, k), which flags an error if k < A[i], but otherwise sets A[i] = k and then updates the d-ary maxheap structure appropriately. Analyze its running time in terms of d and n.

Procedure	Binary heap (worst-case)	Fibonacci heap (amortized)
MAKE-HEAP	$\Theta(1)$	Θ(1)
Insert	$\Theta(\lg n)$	$\Theta(1)$
MINIMUM	$\Theta(1)$	$\Theta(1)$
EXTRACT-MIN	$\Theta(\lg n)$	$O(\lg n)$
Union	$\Theta(n)$	$\Theta(1)$
DECREASE-KEY	$\Theta(\lg n)$	$\Theta(1)$
DELETE	$\Theta(\lg n)$	$O(\lg n)$

- **b.** Show how to compute shortest paths from a single source on an  $\epsilon$ -dense directed graph G = (V, E) with no negative-weight edges in O(E) time. (*Hint:* Pick d as a function of  $\epsilon$ .)
- c. Show how to solve the all-pairs shortest-paths problem on an  $\epsilon$ -dense directed graph G = (V, E) with no negative-weight edges in O(VE) time.
- d. Show how to solve the all-pairs shortest-paths problem in O(VE) time on an  $\epsilon$ -dense directed graph G = (V, E) that may have negative-weight edges but has no negative-weight cycles.